

CS 6423

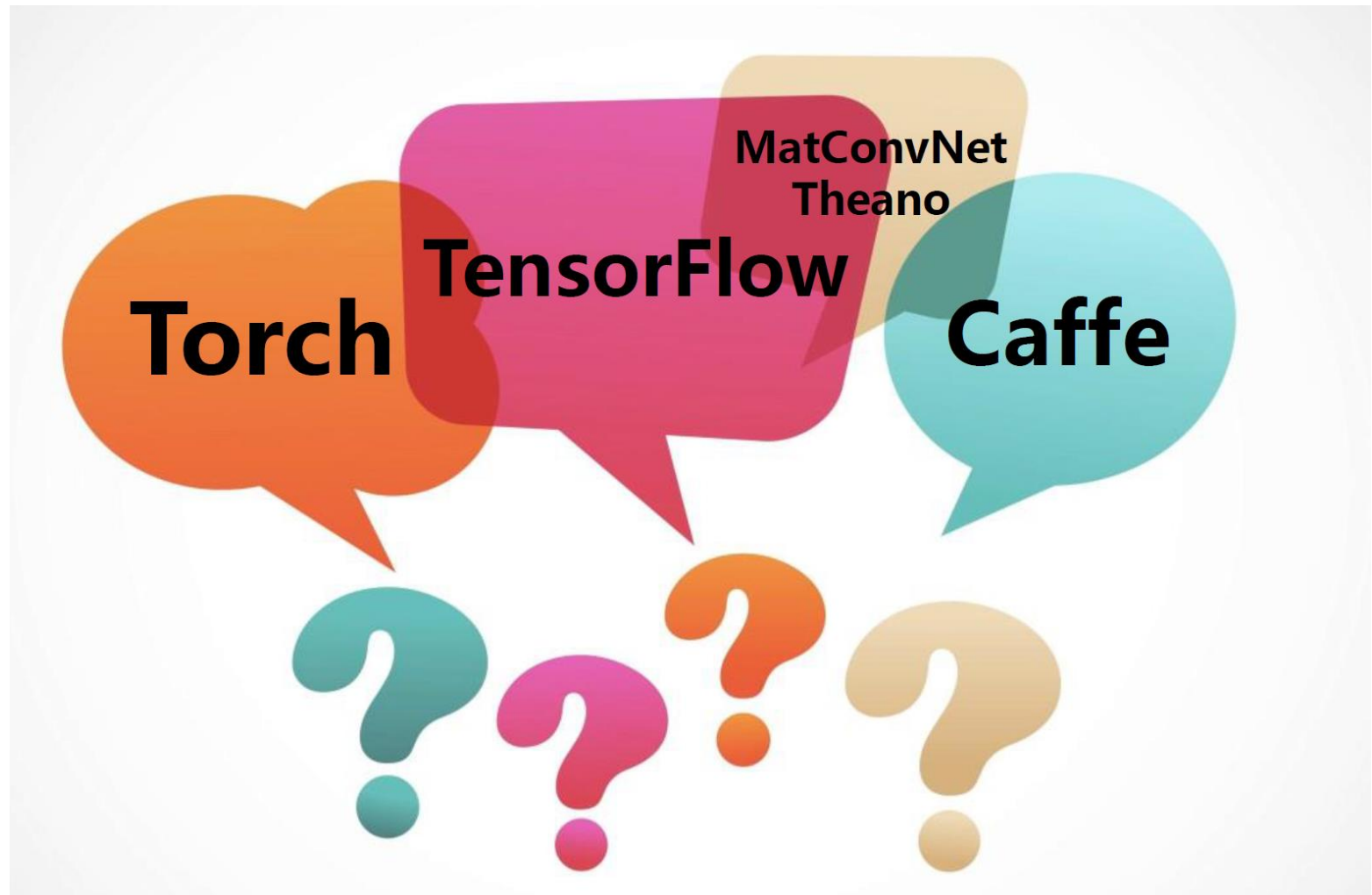
Scalable Computing for Data Analytics

Lecture 13: TensorFlow

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DEEP LEARNING LIBRARIES



BASIC WORKFLOW OF TF

1. Load data
2. Define the NN structure
3. Set optimization parameters
4. Run!



EXAMPLE 1

 terryum Update 2_LogisticRegression_MNIST_160516.ipynb	
 1_LinearRegression_160516.ipynb	Add files via upload
 2_LogisticRegression_MNIST_160516.ipynb	Update 2_LogisticReg
 3a_MLP_MNIST_160516.ipynb	Add files via upload
 3b_MLP_MNIST_Modern_160517.ipynb	Add files via upload
 4a_CNN_MNIST_160517.ipynb	Add files via upload
 README.md	Update README.md

Google CoLab exercises

Other repositories:

https://github.com/terryum/TensorFlow_Exercises



1. LOAD DATA

https://github.com/terryum/TensorFlow_Exercises/blob/master/2_LogisticRegression_MNIST_160516.ipynb

2. Logistic Regression with MNIST data

```
In [1]: import numpy as np
import tensorflow as tf
import matplotlib.pyplot as plt
from tensorflow.examples.tutorials.mnist import input_data
import %matplotlib inline
```

Load MNIST data

```
In [2]: mnist      = input_data.read_data_sets('data', one_hot=True)
X_train  = mnist.train.images
Y_train  = mnist.train.labels
X_test   = mnist.test.images
Y_test   = mnist.test.labels
```

Extracting data/train-images-idx3-ubyte.gz
Extracting data/train-labels-idx1-ubyte.gz
Extracting data/t10k-images-idx3-ubyte.gz
Extracting data/t10k-labels-idx1-ubyte.gz

```
In [3]: dimX = X_train.shape[1]
dimY = Y_train.shape[1]
nTrain = X_train.shape[0]
nTest = X_test.shape[0]
print ("Shape of (X_train, X_test, Y_train, Y_test)")
print (X_train.shape, X_test.shape, Y_train.shape, Y_test.shape)
```

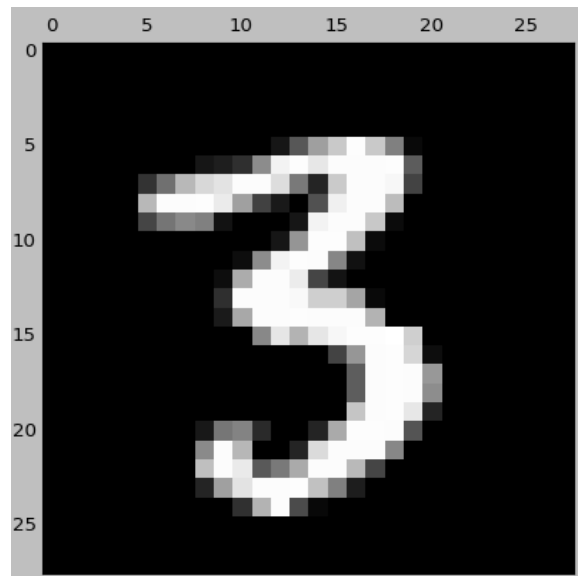
Shape of (X_train, X_test, Y_train, Y_test)
((55000, 784), (10000, 784), (55000, 10), (10000, 10))



1. LOAD DATA

Plot an example image of MNIST data

```
In [4]: myIdx = 36436 # any number  
img = np.reshape(X_train[myIdx, :], (28, 28)) # 28 * 28 = 784  
  
plt.matshow(img, cmap=plt.get_cmap('gray'))  
plt.show()
```



2. DEFINE THE NN STRUCTURE

Write a TF graph

```
In [5]: X = tf.placeholder(tf.float32, [None, dimX], name="input")
        Y = tf.placeholder(tf.float32, [None, dimY], name="output")
        W = tf.Variable(tf.zeros([dimX, dimY]), name="weight")
        b = tf.Variable(tf.zeros([dimY]), name="bias")
```

The output of the logic regression is $\text{softmax}(Wx + b)$

Note that the dimension of Y_{pred} is $(n\text{Batch}, \text{dimY})$

```
In [6]: Y_pred = tf.nn.softmax(tf.matmul(X, W) + b)
```

3. SET OPTIMIZATION PARAMETERS

```
In [7]: loss = tf.reduce_mean(-tf.reduce_sum(Y*tf.log(Y_pred), reduction_indices=1))
```

```
In [8]: learning_rate = 0.005
        optimizer = tf.train.GradientDescentOptimizer(learning_rate).minimize(loss)
        training_epochs = 50
        display_epoch = 5
        batch_size = 100 # For each time, we will use 100 samples to update parameters
```



4. RUN

```
In [11]: with tf.Session() as sess:
          sess.run(tf.initialize_all_variables())

          for epoch in range(training_epochs):
              nBatch = int(nTrain/batch_size)
              myIdx = np.random.permutation(nTrain)
              for ii in range(nBatch):
                  X_batch = X_train[myIdx[ii*batch_size:(ii+1)*batch_size],:]
                  Y_batch = Y_train[myIdx[ii*batch_size:(ii+1)*batch_size],:]
                  sess.run(optimizer, feed_dict={X:X_batch, Y:Y_batch})
```

```
(epoch 40)
[Loss / Training Accuracy] 0.3436 / 0.9047
```

```
(epoch 45)
[Loss / Training Accuracy] 0.3375 / 0.9066
```

```
(epoch 50)
[Loss / Training Accuracy] 0.3322 / 0.9078
```

```
[Test Accuracy] 0.9142
```



4. RUN (C.F.)

Compare prediction with the true value

`argmax(X,1)` returns the index of maximum value (which represents the label in this example) across the columns of the tensor `X`

```
In [9]: correct_prediction = tf.equal(tf.argmax(Y_pred, 1), tf.argmax(Y, 1))
```

```
In [10]: accuracy = tf.reduce_mean(tf.cast(correct_prediction, "float"))
```

Run the session

We use `with` for load a TF session

```
In [11]: with tf.Session() as sess:
    sess.run(tf.initialize_all_variables())

    for epoch in range(training_epochs):
        nBatch = int(nTrain/batch_size)
        myIdx = np.random.permutation(nTrain)
        for ii in range(nBatch):
            X_batch = X_train[myIdx[ii*batch_size:(ii+1)*batch_size],:]
            Y_batch = Y_train[myIdx[ii*batch_size:(ii+1)*batch_size],:]
            sess.run(optimizer, feed_dict={X:X_batch, Y:Y_batch})

        if (epoch+1) % display_epoch == 0:
            loss_temp = sess.run(loss, feed_dict={X: X_train, Y:Y_train})
            accuracy_temp = accuracy.eval({X: X_train, Y:Y_train})
            print "(epoch {})".format(epoch+1)
            print "[Loss / Training Accuracy] {:.4f} / {:.4f}".format(loss_temp, accuracy_temp)
            print " "

    print "[Test Accuracy] ", accuracy.eval({X: X_test, Y: Y_test})
```



EXAMPLE 2

 terryum Update 2_LogisticRegression_MNIST_160516.ipynb	
 1_LinearRegression_160516.ipynb	Add files via upload
 2_LogisticRegression_MNIST_160516.ipynb	Update 2_LogisticReg
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 4a_CNN_MNIST_160517.ipynb	Add files via upload
 README.md	Update README.md

https://github.com/terryum/TensorFlow_Exercises



NEURAL NETWORK

• Basic NN structure

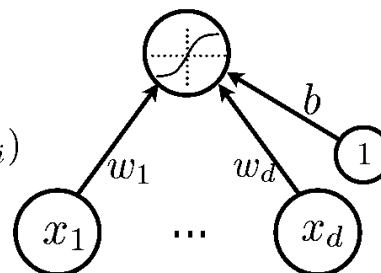
- Neuron pre-activation (or input activation):

$$a(\mathbf{x}) = b + \sum_i w_i x_i = b + \mathbf{w}^\top \mathbf{x}$$

- Neuron (output) activation

$$h(\mathbf{x}) = g(a(\mathbf{x})) = g(b + \sum_i w_i x_i)$$

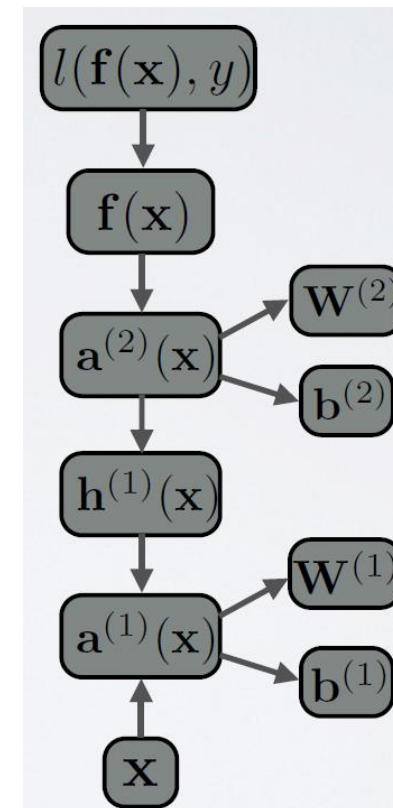
- $\mathbf{w}$ are the connection weights



• Activation functions

Name	Function $y=f(x)$	Derivative $\partial y / \partial x$
Logistic	$\frac{1}{1+e^{-x}}$ 	$y(1-y)$ 
Tanh	$\tanh(x)$ 	$1-y^2$ 
Gaussian	$e^{-x^2/2}$ 	$-x e^{-x^2/2}$ 
Linear	x 	1 

<http://goo.gl/qMQk5H>



1. LOAD DATA

https://github.com/terryum/TensorFlow_Exercises/blob/master/3a_MLP_MNIST_160516.ipynb

3. Multilayer Perceptron with MNIST data

```
In [1]: import numpy as np
import tensorflow as tf
import matplotlib.pyplot as plt
from tensorflow.examples.tutorials.mnist import input_data
from %matplotlib inline
```

Load MNIST data

```
In [2]: mnist      = input_data.read_data_sets('data', one_hot=True)
X_train  = mnist.train.images
Y_train  = mnist.train.labels
X_test   = mnist.test.images
Y_test   = mnist.test.labels
```

```
Extracting data/train-images-idx3-ubyte.gz
Extracting data/train-labels-idx1-ubyte.gz
Extracting data/t10k-images-idx3-ubyte.gz
Extracting data/t10k-labels-idx1-ubyte.gz
```

```
In [3]: dimX = X_train.shape[1]
dimY = Y_train.shape[1]
nTrain = X_train.shape[0]
nTest = X_test.shape[0]
print ("Shape of (X_train, X_test, Y_train, Y_test)")
print (X_train.shape, X_test.shape, Y_train.shape, Y_test.shape)
```

```
Shape of (X_train, X_test, Y_train, Y_test)
((55000, 784), (10000, 784), (55000, 10), (10000, 10))
```



2. DEFINE THE NN STRUCTURE

Define my neural network structure

```
In [4]: nLayer0 = dimX
nLayer1 = 256
nLayer2 = 256
nLayer3 = dimY
sigma_init = 0.1  # For randomized initialization
```

```
In [7]: W = {
    'W1': tf.Variable(tf.random_normal([nLayer0, nLayer1], stddev = sigma_init)),
    'W2': tf.Variable(tf.random_normal([nLayer1, nLayer2], stddev = sigma_init)),
    'W3': tf.Variable(tf.random_normal([nLayer2, nLayer3], stddev = sigma_init))
}
b = {
    'b1': tf.Variable(tf.random_normal([nLayer1])),
    'b2': tf.Variable(tf.random_normal([nLayer2])),
    'b3': tf.Variable(tf.random_normal([nLayer3]))
}
```

```
In [8]: def model_myNN(_X, _W, _b):
    Layer1 = tf.nn.sigmoid(tf.add(tf.matmul(_X, _W['W1']), _b['b1']))
    Layer2 = tf.nn.sigmoid(tf.add(tf.matmul(Layer1, _W['W2']), _b['b2']))
    Layer3 = tf.add(tf.matmul(Layer2, _W['W3']), _b['b3'])
    #Layer3 = tf.nn.sigmoid(tf.add(tf.matmul(Layer2, _W['W3']), _b['b3']))
    return Layer3
```

```
In [9]: X = tf.placeholder(tf.float32, [None, dimX], name="input")
Y = tf.placeholder(tf.float32, [None, dimY], name="output")
```

```
In [10]: Y_pred = model_myNN(X, W, b)
```



3. SET OPTIMIZATION PARAMETERS

Define loss function, optimizer, measurer

We use `softmax_cross_entropy()` and `AdamOptimizer()`

```
In [9]: loss = tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(Y_pred, Y))
```

```
In [10]: learning_rate = 0.001
optimizer = tf.train.AdamOptimizer(learning_rate=learning_rate).minimize(loss)
#optimizer = tf.train.GradientDescentOptimizer(learning_rate).minimize(loss)
training_epochs = 30
display_epoch = 5
batch_size = 100    # For each time, we will use 100 samples to update parameters
```

```
In [11]: correct_prediction = tf.equal(tf.argmax(Y_pred, 1), tf.argmax(Y, 1))
accuracy = tf.reduce_mean(tf.cast(correct_prediction, "float"))
```



4. RUN

```
In [12]: with tf.Session() as sess:
    sess.run(tf.initialize_all_variables())

    for epoch in range(training_epochs):
        nBatch = int(nTrain/batch_size)
        myIdx = np.random.permutation(nTrain)
        for ii in range(nBatch):
            X_batch = X_train[myIdx[ii*batch_size:(ii+1)*batch_size],:]
            Y_batch = Y_train[myIdx[ii*batch_size:(ii+1)*batch_size],:]
            #print X_batch.shape, Y_batch.shape
            sess.run(optimizer, feed_dict={X:X_batch, Y:Y_batch})

        if (epoch+1) % display_epoch == 0:
            loss_temp = sess.run(loss, feed_dict={X: X_train, Y:Y_train})
            accuracy_temp = accuracy.eval({X: X_train, Y:Y_train})
            print "(epoch {})".format(epoch+1)
            print "[Loss / Training Accuracy] {:.05.4f} / {:.05.4f}".format(loss_temp, accuracy_
temp)

            print " "

    print "[Test Accuracy] ", accuracy.eval({X: X_test, Y: Y_test})
```

```
(epoch 45)
[Loss / Training Accuracy] 0.0000 / 1.0000
```

```
(epoch 50)
[Loss / Training Accuracy] 0.0002 / 1.0000
```

```
[Test Accuracy] 0.9799
```



EXAMPLE 3

 terryum Update 2_LogisticRegression_MNIST_160516.ipynb	
 1_LinearRegression_160516.ipynb	Add files via upload
 2_LogisticRegression_MNIST_160516.ipynb	Update 2_LogisticReg
 3a_MLP_MNIST_160516.ipynb	Add files via upload
 3b_MLP_MNIST_Modern_160517.ipynb	Add files via upload
 4a_CNN_MNIST_160517.ipynb	Add files via upload
 README.md	Update README.md

**[https://github.com/terryum/TensorFlow
_Exercises](https://github.com/terryum/TensorFlow_Exercises)**



CONVOLUTION

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Image

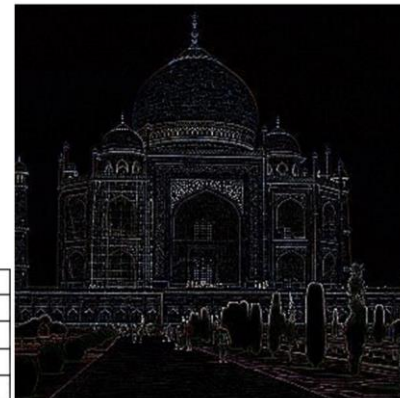
4		

Convolved
Feature

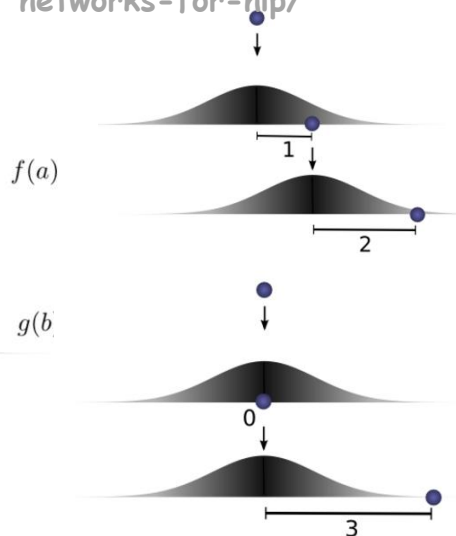
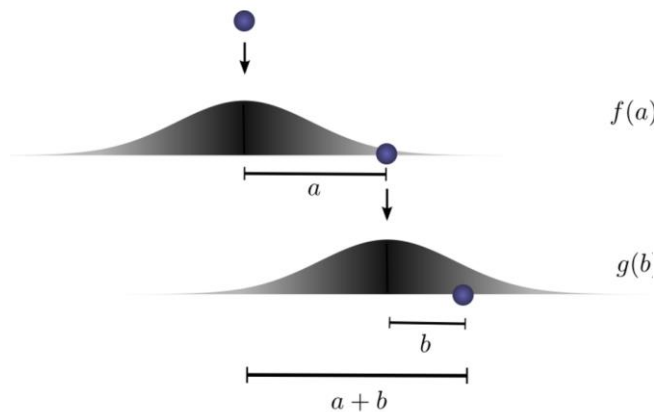
0	0	0	0	0
0	1	1	1	0
0	1	1	1	0
0	1	1	1	0
0	0	0	0	0



0	1	0	
1	-4	1	
0	1	0	



<http://www.wildml.com/2015/11/understanding-convolutional-neural-networks-for-nlp/>



$$\dots f(0) \cdot g(3) + f(1) \cdot g(2) + f(2) \cdot g(1) \dots$$

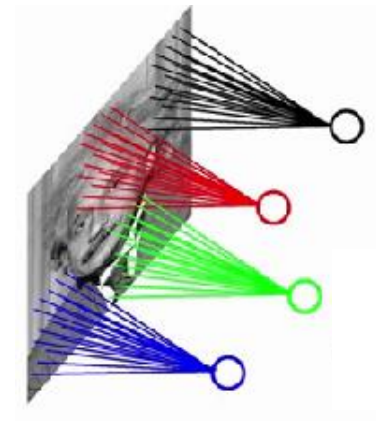
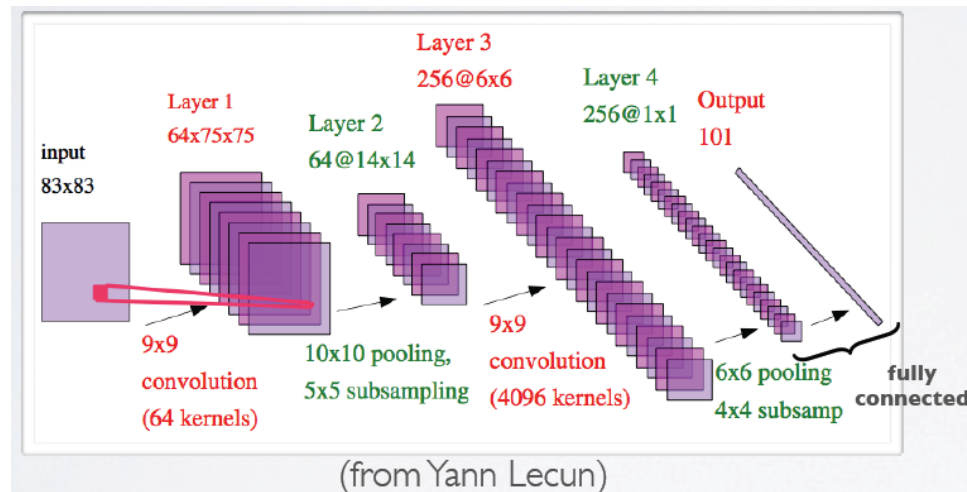
$$(f * g)(c) = \sum_{a+b=c} f(a) \cdot g(b)$$

$$(f * g)(c) = \sum_a f(a) \cdot g(c - a)$$

<http://colah.github.io/posts/2014-07-Understanding-Convolutions/>

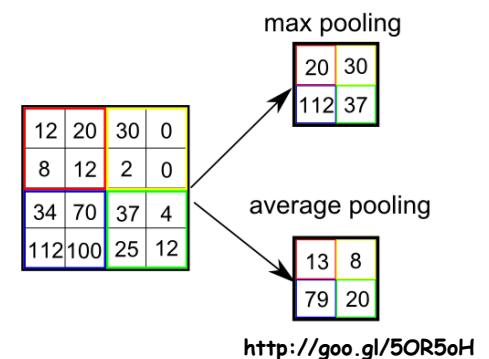
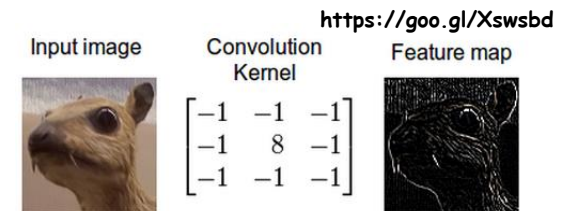


CONVOLUTIONAL NN



- How can we deal with real images which is much bigger than MNIST digit images?

- Use not fully-connected, but locally-connected NN
- Use convolutions to get various feature maps
- Abstract the results into higher layer by using pooling
- Fine tune with fully-connected NN



1. LOAD DATA

https://github.com/terryum/TensorFlow_Exercises/blob/master/4a_CNN_MNIST_160517.ipynb

4. Convolutional Neural Network with MNIST data

```
In [1]: import numpy as np
import tensorflow as tf
import matplotlib.pyplot as plt
from tensorflow.examples.tutorials.mnist import input_data
from %matplotlib inline
```

Load MNIST data

```
In [2]: mnist      = input_data.read_data_sets('data', one_hot=True)
X_train = mnist.train.images
Y_train = mnist.train.labels
X_test  = mnist.test.images
Y_test  = mnist.test.labels
```

```
Extracting data/train-images-idx3-ubyte.gz
Extracting data/train-labels-idx1-ubyte.gz
Extracting data/t10k-images-idx3-ubyte.gz
Extracting data/t10k-labels-idx1-ubyte.gz
```

```
In [3]: dimX = X_train.shape[1]
dimY = Y_train.shape[1]
nTrain = X_train.shape[0]
nTest = X_test.shape[0]
print ("Shape of (X_train, X_test, Y_train, Y_test)")
print (X_train.shape, X_test.shape, Y_train.shape, Y_test.shape)
```

```
Shape of (X_train, X_test, Y_train, Y_test)
((55000, 784), (10000, 784), (55000, 10), (10000, 10))
```



2. DEFINE THE NN STRUCTURE

Set parameters for my CNN structure

```
In [4]: pp = {
    'nLayerIn': dimX,
    'nLayerOut': dimY,
    'sigma_init': 0.1,
    'myDropProb': 0.7,

    'nWin_conv1': 3,
    'nStr_conv1': 1,
    'nPad_conv1': 'SAME', # or 'VALID'
    'nWin_pool1': 2,
    'nStr_pool1': 2,
    'nPad_pool1': 'SAME',
    'nFeat1': 64,

    'nWin_conv2': 3,
    'nStr_conv2': 1,
    'nPad_conv2': 'SAME',
    'nWin_pool2': 2,
    'nStr_pool2': 2,
    'nPad_pool2': 'SAME',
    'nFeat2': 128,

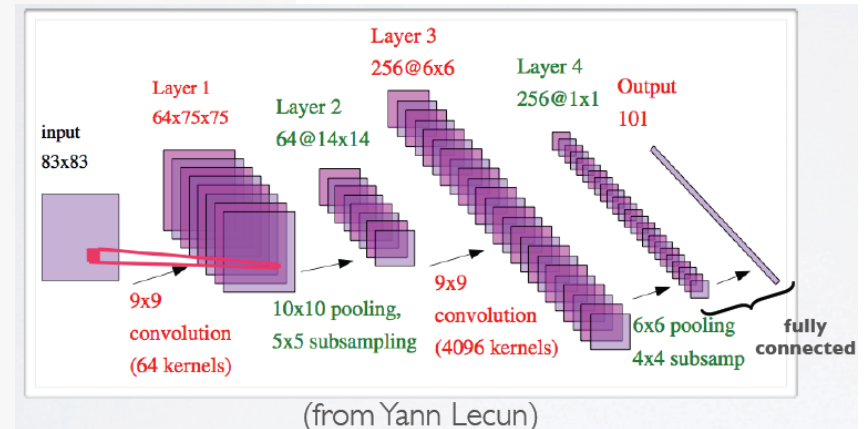
    'dimX_mat': 28, # 28*28 = 784
    'nDimReduce': 7, # dimX_mat/nWin_pool1/nWin_pool2
    'nFull': 1024
}
```

1 _{x1}	1 _{x0}	1 _{x1}	0	0
0 _{x0}	1 _{x1}	1 _{x0}	1	0
0 _{x1}	0 _{x0}	1 _{x1}	1	1
0	0	1	1	0
0	1	1	0	0

Image

4		

Convolved
Feature



2. DEFINE THE NN STRUCTURE

```
In [5]: W = {
    'W_conv1': tf.Variable(tf.truncated_normal([pp['nWin_conv1'], pp['nWin_conv1'], 1, pp['nFeat1']], stddev=pp['sigma_init'], dtype=tf.float32)),
    'W_conv2': tf.Variable(tf.truncated_normal([pp['nWin_conv2'], pp['nWin_conv2'], 1, pp['nFeat1'], pp['nFeat2']], stddev=pp['sigma_init'], dtype=tf.float32)),
    'W_full': tf.Variable(tf.truncated_normal([pp['nDimReduce']*pp['nDimReduce']*pp['nFeat2'], pp['nFull']], stddev=pp['sigma_init'], dtype=tf.float32)),
    'W_out': tf.Variable(tf.truncated_normal([pp['nFull'], pp['nLayerOut']], stddev=pp['sigma_init'], dtype=tf.float32))
}
b = {
    'b_conv1': tf.Variable(tf.truncated_normal([pp['nFeat1']], stddev=pp['sigma_init'], dtype=tf.float32)),
    'b_conv2': tf.Variable(tf.truncated_normal([pp['nFeat2']], stddev=pp['sigma_init'], dtype=tf.float32)),
    'b_full': tf.Variable(tf.truncated_normal([pp['nFull']], stddev=pp['sigma_init'], dtype=tf.float32)),
    'b_out': tf.Variable(tf.truncated_normal([pp['nLayerOut']], stddev=pp['sigma_init'], dtype=tf.float32))
}
```

```
In [6]: def model_myCNN(_X, _W, _B, _dropout_prob, _pp):

    _X_mat = tf.reshape(_X, shape=[-1, _pp['dimX_mat'], _pp['dimX_mat'], 1])

    # L1: Convolution
    _L1_conv = tf.nn.relu(tf.nn.bias_add(
        tf.nn.conv2d(_X_mat, _W['W_conv1'], strides=[1, _pp['nStr_conv1'], _pp['nStr_conv1'], 1], padding=_pp['padding'],
        ), _B['b_conv1']))
    _L1_pool = tf.nn.max_pool(_L1_conv, ksize=[1, _pp['nWin_pool1'], _pp['nWin_pool1'], 1], strides=[1, _pp['nStr_pool1'], _pp['nStr_pool1'], 1],
    _L1_pool2 = tf.nn.dropout(_L1_pool, _dropout_prob)

    # L2: Convolution
    _L2_conv = tf.nn.relu(tf.nn.bias_add(
        tf.nn.conv2d(_L1_pool2, _W['W_conv2'], strides=[1, _pp['nStr_conv2'], _pp['nStr_conv2'], 1], padding=_pp['padding'],
        ), _B['b_conv2']))
    _L2_pool = tf.nn.max_pool(_L2_conv, ksize=[1, _pp['nWin_pool2'], _pp['nWin_pool2'], 1], strides=[1, _pp['nStr_pool2'], _pp['nStr_pool2'], 1],
    _L2_pool2 = tf.nn.dropout(_L2_pool, _dropout_prob)

    # L_full: Fully-connected
    _L2_pool2_vec = tf.reshape(_L2_pool2, [-1, _W['W_full'].get_shape().as_list()[0]])
    _L_full = tf.nn.relu(tf.add(tf.matmul(_L2_pool2_vec, _W['W_full']), _B['b_full']))
    _L_full2 = tf.nn.dropout(_L_full, _dropout_prob)

    # L_full: Output
    _L_out = tf.add(tf.matmul(_L_full2, _W['W_out']), _B['b_out'])

    # Return
    out = {
        'X_mat': _X_mat,
        'L1_conv': _L1_conv, 'L1_pool': _L1_pool, 'L1_pool2': _L1_pool2, # After dropout
        'L2_conv': _L2_conv, 'L2_pool': _L2_pool, 'L2_pool2': _L2_pool2,
        'L_full': _L_full, 'L_full2': _L_full2, 'L_out': _L_out
    }
    return out
```

3. SET OPTIMIZATION PARAMETERS

Define variables and optimizer

```
In [7]: X = tf.placeholder(tf.float32, [None, dimX], name="input")
        Y = tf.placeholder(tf.float32, [None, dimY], name="output")
        dropout_prob = tf.placeholder(tf.float32, name="dropout")
```

```
In [8]: Y_pred_all = model_myCNN(X, W, b, dropout_prob, pp)
        Y_pred = Y_pred_all['L_out']
```

```
In [9]: loss = tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(Y_pred, Y))
        learning_rate = 0.001
        optimizer = tf.train.AdamOptimizer(learning_rate=learning_rate).minimize(loss)
        training_epochs = 5
        display_epoch = 1
        batch_size = 100  # For each time, we will use 100 samples to update ppeters
```

```
In [10]: correct_prediction = tf.equal(tf.argmax(Y_pred, 1), tf.argmax(Y, 1))
        accuracy = tf.reduce_mean(tf.cast(correct_prediction, "float"))
```



4. RUN

In [11]: *# Because of the memory allocation problem in evaluation*

```
divide_train = 50;
divide_test = 10;
nTrainSub = (int)(nTrain/divide_train);
nTestSub = (int)(nTest/divide_test);
```

In [12]: *#with tf.Session() as sess:*

```
sess = tf.InteractiveSession()
sess.run(tf.initialize_all_variables())

for epoch in range(training_epochs):
    nBatch = int(nTrain/batch_size)
    #myIdx = np.random.permutation(nTrain)
    for ii in range(nBatch):
        X_Batch, Y_Batch = mnist.train.next_batch(batch_size)
        #X_Batch = X_train[myIdx[ii*batch_size:(ii+1)*batch_size],:]
        #Y_Batch = Y_train[myIdx[ii*batch_size:(ii+1)*batch_size],:]
        sess.run(optimizer, feed_dict={X:X_Batch, Y:Y_Batch, dropout_prob:pp['myDropProb']})

    if (epoch+1) % display_epoch == 0:
        # Because of the memory allocation problem in evaluation
        loss_temp = accuracy_train_temp = accuracy_test_temp = 0
        for jj in range(divide_train):
            loss_temp += sess.run(loss, feed_dict={X: X_train[jj*divide_train:(jj+1)*divide_train,:], Y:Y_train[jj*
            accuracy_train_temp += accuracy.eval({X: X_train[jj*divide_train:(jj+1)*divide_train,:], Y:Y_train[jj*
        for kk in range(divide_test):
            accuracy_test_temp += accuracy.eval({X: X_test[kk*divide_test:(kk+1)*divide_test,:], Y: Y_test[kk*divid

        print "(epoch {})".format(epoch+1)
        print "[Loss / Tranining Accuracy / Test Accuracy] {:.05.4f} / {:.05.4f} / {:.05.4f}".format(loss_temp/divide
        print " "

print "[Test Accuracy] {:.05.4f}".format(accuracy_test_temp/divide_test)
```

(epoch 4)

[Loss / Tranining Accuracy / Test Accuracy] 0.0189 / 0.9940 / 1.0000

(epoch 5)

[Loss / Tranining Accuracy / Test Accuracy] 0.0155 / 0.9960 / 1.0000

[Test Accuracy] 1.0000



4. RUN (C.F.)

Let's see the learned features

```
In [13]: nExample = 223

Y_pred_all = model_myCNN(X, W, b, dropout_prob, pp)
X_mat = sess.run(Y_pred_all['X_mat'], feed_dict={X: X_train[nExample-1:nExample, :]})
L1_conv = sess.run(Y_pred_all['L1_conv'], feed_dict={X: X_train[nExample-1:nExample, :]})
```

```
In [14]: # (nExample)th Input
plt.matshow(X_mat[0, :, :, 0], cmap=plt.get_cmap('gray'))
plt.colorbar()
plt.show()
```

```
In [15]: # Features
nFeature = 40
plt.matshow(L1_conv[0, :, :, nFeature], cmap=plt.get_cmap('gray'))
plt.colorbar()
plt.show()
```

```
In [16]: sess.close()
```

