

Counter Programs
Turing Machines and ...

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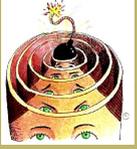
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Lecture 40: Another Model of Computation

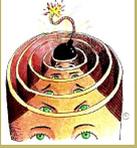
Aims:

- To look at Counter Programs, which are another formal model of computation; and
- To show that Turing machines and Counter Programs are of equivalent power.



40.1. Counter Programs

- Turing machines are only one of many formal models of computation.
- Here we describe *Counter Programs*, which are another very simple formal model.
- Counter Programs or something very like them also go under the names Counter Machines, Register Machines, Minsky Machines, etc.
- A Counter Program has a finite set of variables.
- Each variable can store a natural number (i.e. a non-negative integer).
- A Counter Program is a finite *sequence* of labelled commands, the last of which is **halt**
- The other allowable commands are:
 - $x := 0$
 - $x := y + 1$
 - $x := y - 1$ (In Counter Programs, $y - 1$ is defined to be zero if y is already 0)
 - **if** $x = 0$ **goto** G (where G is the label of a command in the Program)
- The commands are executed in sequence, but branching off to the specified command when a **goto** is encountered, and terminating when the final command in the sequence (**halt**) is encountered.
- **Example 1.** A Counter Program having variables u , x and y which, if started in configuration $\langle u = u_0, x = x_0, y = y_0 \rangle$, will halt in configuration $\langle u = 0, x = x_0 + y_0, y = 0 \rangle$. In other words, it adds the initial contents of x and y and stores the result in x , also destroying the value that was in y . E.g. if initially x contains 3 and y contains 2, then afterwards x will contain 5 and y will contain 0.



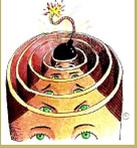
Note the role of u .

```
1.  $u := 0$ ;  
2. if  $y = 0$  goto 6;  
3.  $y := y - 1$ ;  
4.  $x := x + 1$ ;  
5. if  $u = 0$  goto 2;  
6. halt
```

- Trace the program for initial configuration $\langle u = 28, x = 3, y = 2 \rangle$.
- **Example 2.** A Counter Program which, if started in configuration $\langle u = u_0, v = v_0, x = x_0, y = y_0, z = z_0 \rangle$, will halt in configuration $\langle u = 0, v = 0, x = 0, y = y_0, z = x_0 \times y_0 \rangle$. In other words, it multiplies the initial contents of x and y and stores the result in z , also destroying the value that was in x . u has the same role as before.

Note the trick we use to copy y into v . And note that the second half of the program is effectively the adding program from Example 1.

```
1.  $u := 0$ ;  
2.  $z := 0$ ;  
3. if  $x = 0$  goto 11;  
4.  $x := x - 1$ ;  
5.  $v := y + 1$ ;  
6.  $v := v - 1$ ;  
7. if  $v = 0$  goto 3;  
8.  $v := v - 1$ ;  
9.  $z := z + 1$ ;  
10. if  $u = 0$  goto 7;  
11. halt
```



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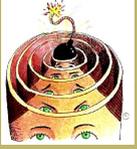
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- Just as with Turing machines, Counter Programs can be defined in many different ways that are of equivalent power:
 - E.g. restricting yourself to only two variables;
 - E.g. insisting that one register is used for the answer, and the rest are cleared by the end of the computation;
 - E.g. allowing infinitely many variables;
 - E.g. using slightly different commands.



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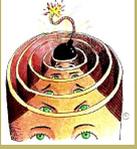
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40.2. Turing Machines and Counter Programs are of Equivalent Power

- Turing machines and Counter Programs are of equivalent power: any problem that can be solved by a Turing machine can be solved by a Counter Program, and *vice versa*.
- This is by no mean obvious: they seem like very different models of computation.
- We prove this by showing that
 - anything a Turing machine can do, a Counter Program can do — i.e., given a Turing machine, we show how to build a Counter Program that performs the same computation; and
 - anything a Counter Program can do, a Turing machine can do — i.e., given a Counter Program, we show how to build a Turing machine that performs the same computation.
- One possibly useful observation is that both models have a potentially infinite amount of memory: for Turing machines this comes in the form of its infinite tape; Counter Programs have a finite set of variables but each can hold an arbitrarily large value.

40.2.1. Using a Counter Program to Simulate a Turing Machine

- The first challenge is how to represent the contents of the tape as one or more numbers that can be stored in the variables of a Counter Program. This is possible because, although the tape is infinite, only finitely many cells are non-blank.
- Each member of Σ must be associated with a natural number (non-negative number).



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- E.g. if $\Sigma = \{a, b, X, _ \}$,

a	:	0	b	:	1
X	:	2	$_$:	3

- Then, if you have a sequence of characters $c_1, c_2, c_3, \dots, c_n$ and their corresponding numbers are $d_1, d_2, d_3, \dots, d_n$, then these numbers can be combined into a single, unique number:

$$2^{d_1} \times 3^{d_2} \times 5^{d_3} \times \dots \times p_n^{d_n}$$

where p_i is the i th prime number. (Fundamental Theorem of Arithmetic!)

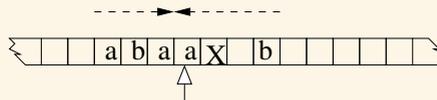
- E.g. $aabX_bbX$ becomes $2^0 \times 3^0 \times 5^1 \times 7^2 \times 11^3 \times 13^1 \times 17^1 \times 19^2 = 26016185200$ (and no other string of characters map to the same number).
- In fact, for reasons we needn't go into, the above is a simplification. And, instead, we have to use a slight variant, such as:

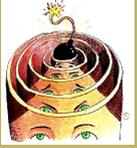
$$2^{d_1+1} \times 3^{d_2+1} \times 5^{d_3+1} \times \dots \times p_n^{d_n+1}$$

- We can use two numbers to encode
 - the cells from the leftmost non-blank up to but excluding the scanned symbol;
 - and
 - the cells from the rightmost non-blank up to and including the scanned symbol.

Note how the last of these is encoded 'in reverse'.

- E.g.





$$2^0 \times 3^1 \times 5^0 = 3$$

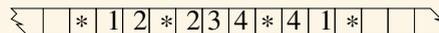
$$2^1 \times 3^3 \times 5^2 \times 7^0 = 1350$$

- So the Counter Program has a variable x to hold the left-hand tape contents, a variable y to hold the right-hand tape contents, and a variable z to hold the Turing machine's state (plus some extra ones to help it get its work done).
- For each entry in the Turing machine's transition table, there is a sequence of Counter Program commands which alter the contents of the three variables.
- E.g. if the Turing machine moves left, we do some arithmetic on x to make it a smaller number and some arithmetic on y to make it a bigger number. (Similarly, for moving right.)
- E.g. if the Turing machine writes a symbol, then we do some arithmetic on y .
- In all cases, we also do some arithmetic on z to reflect the change of state.

40.2.2. Using a Turing Machine to Simulate a Counter Program

- Now the first challenge is how to represent the contents of the Counter Program's variables as symbols on a tape.
- Easy! Let $\Sigma = \{0, \dots, 9, *\}$ and write out the contents of each variable onto the tape, separated by, e.g., $*$'s.
- E.g.

x	y	z
12	234	41



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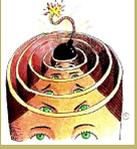
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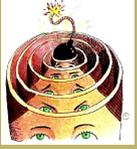
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- In fact, contrary to what is shown in the diagram, you would probably use a binary encoding.
- For each type of command, we can work out a simple Turing machine control unit:
 - E.g. $x := 0$: scan the tape to reach the part that holds the value of x and then do some shifting (e.g. so that $*12*$ becomes $**$)
 - E.g. $x := y + 1$: involves a lot of scanning, shifting and writing.
- Then these basic machines can be combined, just like we were combining simple Turing machines into complex ones earlier.

Acknowledgements

[Har92], [LP81] and [Tru91] were all used to help me to write this lecture.

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