

*Introduction*

*The Totality Problem*

*The Negative Value...*

*Reductions Again*

*The Equivalence Problem*

*Rice's Theorem*

*Concluding Remarks*

[Module Home Page](#)

[Title Page](#)



Page 1 of 14

[Back](#)

[Full Screen](#)

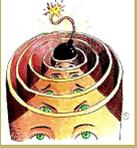
[Close](#)

[Quit](#)

## Lecture 36: Other Non-computable Problems

Aims:

- To show how to prove that other problems are non-computable, which involves reductions from, e.g., the Halting Problem; and
- To point out how few problems are, in fact, computable.



## Introduction

*The Totality Problem*

*The Negative Value...*

*Reductions Again*

*The Equivalence Problem*

*Rice's Theorem*

*Concluding Remarks*

[Module Home Page](#)

[Title Page](#)



Page 2 of 14

[Back](#)

[Full Screen](#)

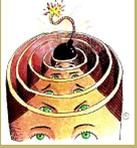
[Close](#)

[Quit](#)

## 36.1. Introduction

- There are many problems for which there is no algorithm. In fact, the number of things which can be computed is infinitesimal compared with the number of things one might like to compute but which cannot be computed.
- To prove a problem  $P$  is non-computable,
  - We could give a proof similar to the one we gave for the Halting Problem. This would be a direct but tedious way of proving non-computability.
  - But there is an indirect way of proving non-computability which is usually easier. We exploit the fact that we already have one problem that has been proved to be non-computable, i.e. the Halting Problem. The proof will still be a proof by contradiction; it will also use a reduction.

We assume that  $P$  is computable. Then we show that, if this assumption is true, then the Halting Problem would be computable. But we know the Halting Problem is non-computable. Contradiction! So our assumption is false:  $P$  is non-computable.



## 36.2. The Totality Problem

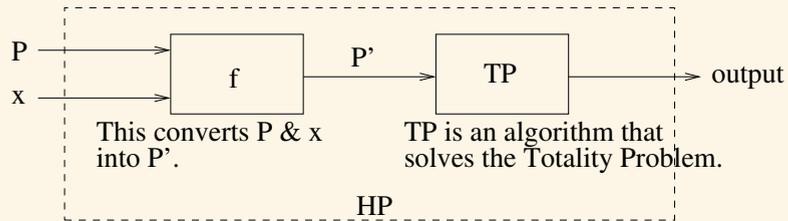
- We'll prove the following is non-computable:

### Problem 36.1. *The Totality Problem*

Parameters: *A MOCCA program  $P$ .*

Returns: *YES if  $P$  would terminate for all its inputs; NO otherwise.*

- Assume that the Totality Problem is computable.
- I.e. we have a MOCCA program  $TP$  that solves the Totality Problem.
- But in that case, we can write a MOCCA program  $HP$  to solve the Halting Problem. It will use program  $TP$  as a procedure.



$HP$  is an algorithm that solves the Halting Problem.

- So,  $HP$  takes in two inputs  $P$  and  $x$ .
- Function  $f$  uses these two inputs to write a new program called  $P'$ , which

Introduction

The Totality Problem

The Negative Value...

Reductions Again

The Equivalence Problem

Rice's Theorem

Concluding Remarks

Module Home Page

Title Page



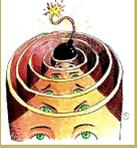
Page 3 of 14

Back

Full Screen

Close

Quit



Introduction

The Totality Problem

The Negative Value...

Reductions Again

The Equivalence Problem

Rice's Theorem

Concluding Remarks

Module Home Page

Title Page



Page 4 of 14

Back

Full Screen

Close

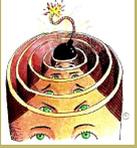
Quit

- takes in an input  $y$  but ignores it;
- runs  $P$  on  $x$

In other words,  $f$  outputs the following program:

```
Algorithm:  $P'(y)$   
// Ignore  $y$   
 $P(x);$ 
```

- $P'$  is then the input to  $TP$  (the program that solves the Totality Problem).
- So we're using  $TP$  to find out whether  $P'$  halts on all inputs.
- But what  $P'$  does is: ignore its input and simply run  $P$  on  $x$ .
- So asking whether  $P'$  halts on all inputs is the same as asking whether  $P$  halts on  $x$ .
- So we've managed to write a program that solves the Halting Problem!
- We know that no such program can exist, so there must be something wrong with what we've done. There's nothing wrong with  $f$ , so the only part that can be held responsible is  $TP$ .
- We conclude that a program  $TP$ , solving the Totality Problem, cannot exist.



### 36.3. The Negative Value Problem

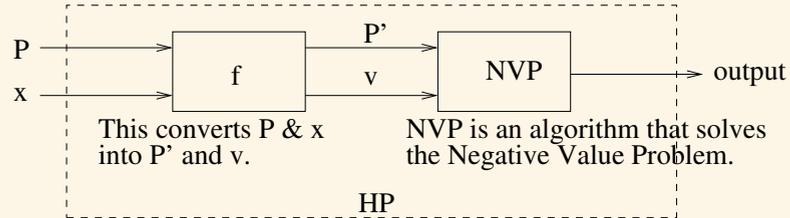
- We'll prove the following is non-computable:

**Problem 36.2.** *The Negative Value Problem*

Parameters: *A MOCCA program  $P$  that does not require any input and a variable  $v$  used in  $P$ .*

Returns: *YES if  $v$  ever gets assigned a negative value when  $P$  is executed; NO otherwise.*

- Assume that the Negative Value Problem is computable.
- I.e. we have a MOCCA program  $NVP$  that solves the Negative Value Problem.
- But in that case, we can write a MOCCA program  $HP$  to solve the Halting Problem. It will use program  $NVP$  as a procedure.



$HP$  is an algorithm that solves the Halting Problem.

- So,  $HP$  takes in two inputs  $P$  and  $x$ .

Introduction

The Totality Problem

The Negative Value...

Reductions Again

The Equivalence Problem

Rice's Theorem

Concluding Remarks

Module Home Page

Title Page

◀ ▶

◀ ▶

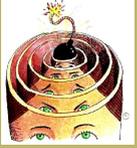
Page 5 of 14

Back

Full Screen

Close

Quit



Introduction

The Totality Problem

The Negative Value . . .

Reductions Again

The Equivalence Problem

Rice's Theorem

Concluding Remarks

Module Home Page

Title Page



Page 6 of 14

Back

Full Screen

Close

Quit

- Function  $f$  scans  $P$  to identify a variable  $v$  that is not used by  $P$  and then writes a new program called  $P'$ , which
  - takes in an input  $y$  but ignores it;
  - runs  $P$  on  $x$ ;
  - then assigns  $-1$  to  $v$ .

In other words,  $f$  outputs the following program:

```
Algorithm:  $P'(y)$   
// Ignore  $y$   
 $P(x)$ ;  
 $v := -1$ ;
```

- $P'$  and  $v$  are then the input to  $NVP$  (the program that solves the Negative Value Problem).
- So we're using  $NVP$  to find out whether  $P'$  assigns a negative value to  $v$ .
- But what  $P'$  does is: ignore its input, run  $P$  on  $x$  and assign  $-1$  to  $v$ .
- So asking whether  $P'$  ever assigns a negative value to  $v$  is the same as asking whether  $P$  halts on  $x$ . (Why? Because we'll only get to the command in which  $-1$  is assigned into  $v$  if  $P$  halts on  $x$ .)
- So we've managed to write a program that solves the Halting Problem!
- We know that no such program can exist, so there must be something wrong with what we've done. There's nothing wrong with  $f$ , so the only part that can be held responsible is  $NVP$ .



- We conclude that a program  $NVP$ , solving the Negative Value Problem, cannot exist.

*Introduction*

*The Totality Problem*

*The Negative Value . . .*

*Reductions Again*

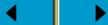
*The Equivalence Problem*

*Rice's Theorem*

*Concluding Remarks*

*Module Home Page*

*Title Page*



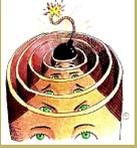
*Page 7 of 14*

*Back*

*Full Screen*

*Close*

*Quit*



Introduction

The Totality Problem

The Negative Value...

Reductions Again

The Equivalence Problem

Rice's Theorem

Concluding Remarks

Module Home Page

Title Page



Page 8 of 14

Back

Full Screen

Close

Quit

## 36.4. Reductions Again

- You can see that, in these proofs, the non-computability of one problem is being established by finding a *reduction* from a problem that is already known to be non-computable.

- In the examples, we have shown

The Halting Problem reduces to The Totality problem

The Halting Problem reduces to The Negative Value Problem

- If  $P_1$  is known to be non-computable and  $P_1$  reduces to  $P_2$ , then  $P_2$  must be non-computable too. The reason is that, otherwise, we could solve  $P_1$  by an algorithm that would transform  $P_1$ 's inputs into a suitable form and ask  $P_2$  for the answer.
- This is like the reductions we were using to show that a problem is **NP**-hard. The difference there was that we also required the reduction to have worst-case polynomial time complexity, whereas here efficiency is not the issue so the reduction can use as much resource as it needs.
- In both cases, once we have such a reduction,  $P_1$  cannot be worse than  $P_2$ .

- It's common to show reductions from the Halting Problem. But any problem that has been proved to be non-computable can be used. E.g. now that we know that the Totality Problem is non-computable, we can use that, if we wish, in future proofs. Indeed, in the next section, we use the Totality Problem to prove the non-computability of the Equivalence Problem. We do this by showing

The Totality Problem reduces to The Equivalence Problem



## 36.5. The Equivalence Problem

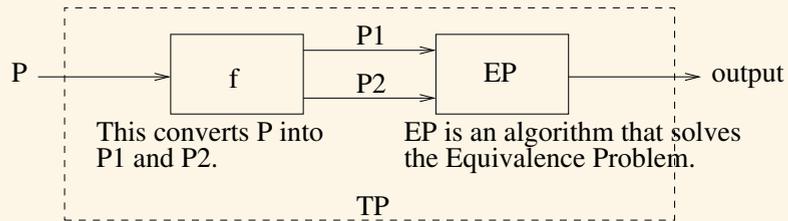
- We'll prove the following is non-computable:

### Problem 36.3. *The Equivalence Problem*

Parameters: *Two MOCCA programs  $P_1$  and  $P_2$ .*

Returns: *YES if  $P_1$  and  $P_2$  solve the same problems (same outputs for same inputs); NO otherwise.*

- Assume that the Equivalence Problem is computable.
- I.e. we have a MOCCA program  $EP$  that solves the Equivalence Problem.
- But in that case, we can write a MOCCA program  $TP$  to solve the Totality Problem. It will use program  $EP$  as a procedure.



This converts  $P$  into  $P_1$  and  $P_2$ .

$EP$  is an algorithm that solves the Equivalence Problem.

$TP$

$TP$  is an algorithm that solves the Totality Problem.

- So,  $TP$  takes in one input  $P$ .

Introduction

The Totality Problem

The Negative Value...

Reductions Again

The Equivalence Problem

Rice's Theorem

Concluding Remarks

Module Home Page

Title Page



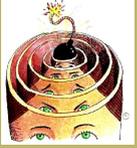
Page 9 of 14

Back

Full Screen

Close

Quit



Introduction

The Totality Problem

The Negative Value...

Reductions Again

The Equivalence Problem

Rice's Theorem

Concluding Remarks

Module Home Page

Title Page



Page 10 of 14

Back

Full Screen

Close

Quit

- Function  $f$  uses this input to write a new program called  $P_1$ , which
  - takes in an input  $x$ ;
  - runs  $P$  on  $x$ ;
  - returns “CS2205” (for example)

and it also writes a new program  $P_2$ , which

- takes in an input  $x$  but ignores it;
- returns “CS2205”

In other words,  $f$  outputs the following programs:

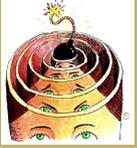
**Algorithm:**  $P_1(x)$

```
P(x);  
return "CS2205";
```

**Algorithm:**  $P_2(x)$

```
// Ignore x  
return "CS2205";
```

- $P_1$  and  $P_2$  are then the input to  $EP$  (the program that solves the Equivalence Problem).
- So we're using  $EP$  to find out whether  $P_1$  and  $P_2$  are equivalent.
- But what  $P_1$  does is run  $P$  on  $x$  and return “CS2205”, and what  $P_2$  does is return “CS2205”.
- So asking whether  $P_1$  and  $P_2$  are equivalent (same outputs for same inputs) is the same as asking whether  $P$  halts on all inputs.



[Introduction](#)

[The Totality Problem](#)

[The Negative Value...](#)

[Reductions Again](#)

[The Equivalence Problem](#)

[Rice's Theorem](#)

[Concluding Remarks](#)

[Module Home Page](#)

[Title Page](#)



Page 11 of 14

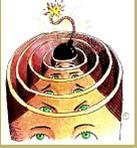
[Back](#)

[Full Screen](#)

[Close](#)

[Quit](#)

- So we've managed to write a program that solves the Totality Problem!
- We know that no such program can exist, so there must be something wrong with what we've done. There's nothing wrong with  $f$ , so the only part that can be held responsible is  $EP$ .
- We conclude that a program  $EP$ , solving the Equivalence Problem, cannot exist.



[Introduction](#)

[The Totality Problem](#)

[The Negative Value...](#)

[Reductions Again](#)

[The Equivalence Problem](#)

[Rice's Theorem](#)

[Concluding Remarks](#)

[Module Home Page](#)

[Title Page](#)



Page 12 of 14

[Back](#)

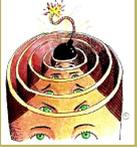
[Full Screen](#)

[Close](#)

[Quit](#)

## 36.6. Rice's Theorem

- Maybe you're feeling that almost any interesting question that we ask about algorithms is not computable. You'd be basically right!
- Virtually all problems that involve writing a program that takes in another program  $P$  and tries to answer a question about the behaviour of  $P$  are non-computable.
- *Rice's Theorem*. Think of a task that some algorithms perform and others do not (such as outputting 28, computing the square root of the input, always giving the same output irrespective of the input, etc). There is no algorithm that can take in an arbitrary program  $P$ , inspect  $P$  and tell whether  $P$  performs that task.
- This has consequences for compilers and virus checkers.



*Introduction*

*The Totality Problem*

*The Negative Value...*

*Reductions Again*

*The Equivalence Problem*

*Rice's Theorem*

*Concluding Remarks*

[Module Home Page](#)

[Title Page](#)



Page 13 of 14

[Back](#)

[Full Screen](#)

[Close](#)

[Quit](#)

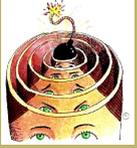
## 36.7. Concluding Remarks

- We've only grazed the surface of this topic!
- Some of the non-computable problems are less computable than others.
- E.g. the Halting Problem and the Totality Problem are both non-computable but the Totality Problem is less computable than the Halting Problem!
- In fact, there is an infinite hierarchy of levels of (non-)computability!

### Acknowledgements

I based some of this on [Har92] and [GL82].

Clip Art (of head with bomb) licensed from the Clip Art Gallery on DiscoverySchool.com.



*Introduction*

*The Totality Problem*

*The Negative Value...*

*Reductions Again*

*The Equivalence Problem*

*Rice's Theorem*

*Concluding Remarks*

[Module Home Page](#)

[Title Page](#)



Page 14 of 14

[Back](#)

[Full Screen](#)

[Close](#)

[Quit](#)

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- [GL82] L. Goldschlager and A. Lister. *Computer Science: A Modern Introduction*. Prentice-Hall, 1982.
- [Har92] D. Harel. *Algorithmics: The Spirit of Computing*. Addison-Wesley, 2nd edition, 1992.